



C1450-XX-VS-1S-YYY Servo Drives

Installation Guide

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1 Important Safety Instructions



For your personal safety

Disregarding the following safety measures can lead to severe injury to persons and damage to material:

- Only use the product as directed.
- Never commission the product in the event of visible damage.
- Never commission the product before assembly has been completed.
- Do not carry out any technical changes on the product.
- Safety of equipment may be impaired if the equipment is used in manner not specified by the manufacturer.
- Only LinMot personnel is allowed to service the product.
- Only use the accessories approved for the product.
- Only use original spare parts from LinMot.
- Observe all regulations for the prevention of accidents, directives and laws applicable on site.
- Transport, installation, commissioning and maintenance work must only be carried out by qualified personnel.
 - Observe IEC 364 and CENELEC HD 384 or DIN VDE 0100 and IEC report 664 or DIN VDE 0110 and all national regulations for the prevention of accidents.
 - According to the basic safety information, qualified, skilled personnel are persons who are familiar with the assembly, installation, commissioning, and operation of the product and who have the qualifications necessary for their occupation.
- Observe all specifications in this documentation.
 - This is the condition for safe and trouble-free operation and the achievement of the specified product features.
 - The procedural notes and circuit details described in this documentation are only proposals. It is up to the user to check whether they can be transferred to the particular applications. NTI AG / LinMot does not accept any liability for the suitability of the procedures and circuit proposals described.
- LinMot servo drives and the accessory components can include live and moving parts (depending on their type of protection) during operation. Surfaces can be hot.
 - Non-authorized removal of the required cover, inappropriate use, incorrect installation or operation create the risk of severe injury to persons or damage to material assets.
 - For more information, please see the documentation.
- High amounts of energy are produced in the drive. Therefore it is required to wear personal protective equipment (body protection, headgear, eye protection, hand guard).

Application as directed

- Drives are components which are designed for installation in electrical systems or machines. They are not to be used as domestic appliances, but only for industrial purposes according to EN 61000-3-2.
- When drives are installed into machines, commissioning (i.e. starting of the operation as directed) is prohibited until it is proven that the machine complies with the regulations of the EC Directive 2006/42/EG (Machinery Directive); EN 60204 must be observed.
- Commissioning (i.e. starting of the operation as directed) is only allowed when there is compliance with the EMC Directive (2014/30/EU).
- The technical data and supply conditions can be obtained from the nameplate and the documentation. They must be strictly observed.

Transport, storage

- Please observe the notes on transport, storage, and appropriate handling.
- Observe the climatic conditions according to the technical data.

Installation

- The drives must be installed and cooled according to the instructions given in the corresponding documentation.
- The ambient air must not exceed degree of pollution 2 according to EN 61800-5-1.
- Ensure proper handling and avoid excessive mechanical stress. Do not bend any components and do not change any insulation distances during transport or handling. Do not touch any electronic components and contacts.
- Drives contain electrostatic sensitive devices which can easily be damaged by inappropriate handling. Do not damage or destroy any electrical components since this might endanger your health!

Electrical connection

- When working on live drives, observe the applicable national regulations for the prevention of accidents.
- The electrical installation must be carried out according to the appropriate regulations (e.g. cable cross-sections, fuses, PE connection). Additional information can be obtained from the documentation.



- This product can cause high-frequency interferences in non-industrial environments which can require measures for interference suppression.

Operation

- If necessary, systems including drives must be equipped with additional monitoring and protection devices according to the valid safety regulations (e.g. law on technical equipment, regulations for the prevention of accidents). The drives can be adapted to your application. Please observe the corresponding information given in the documentation.
- After the drive has been disconnected from the supply voltage, all live components and power connections must not be touched immediately because capacitors can still be charged. Please observe the corresponding stickers on the drive. All protection covers and doors must be shut during operation.

Protection of persons



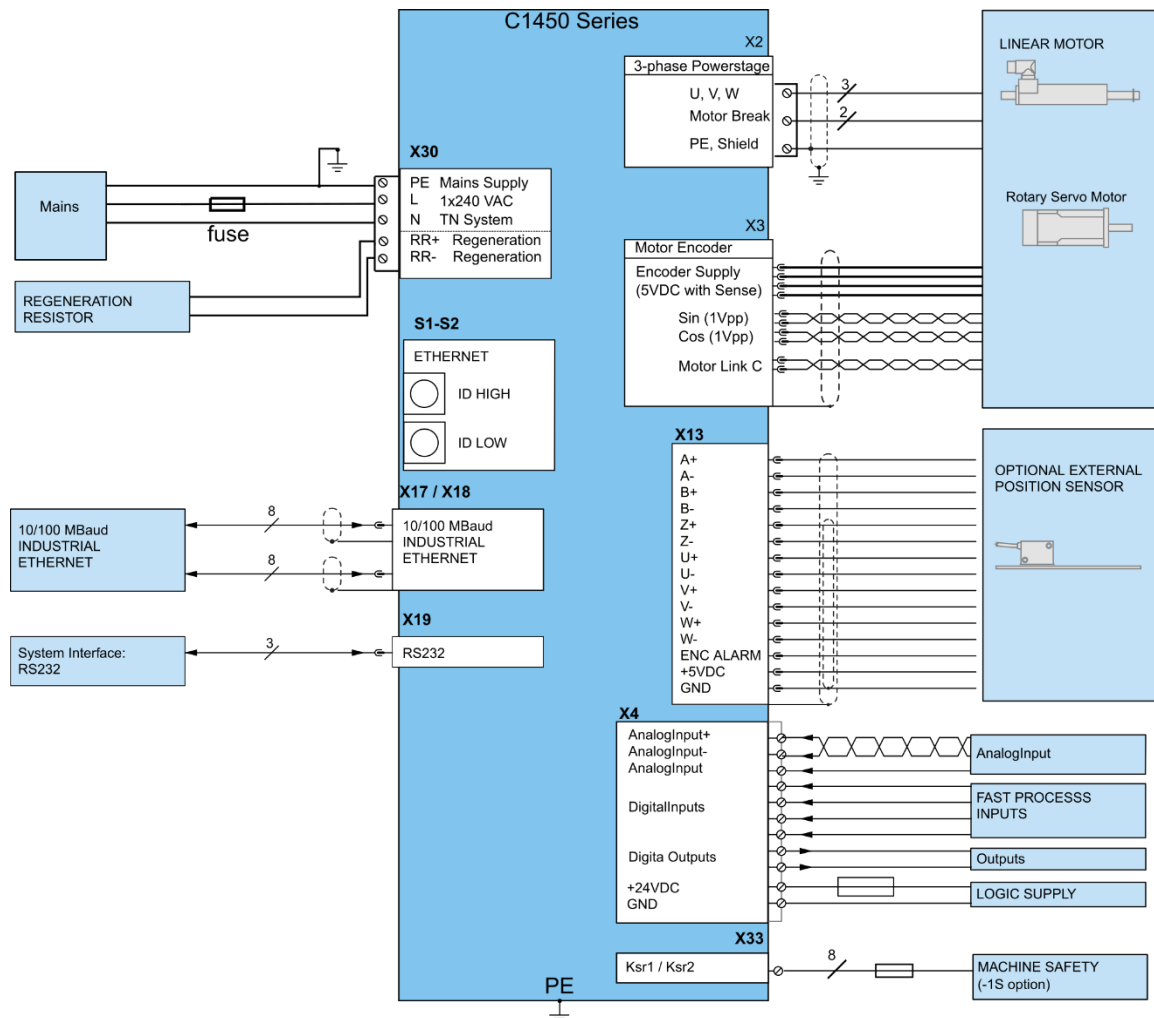
- Before working on the drive, check that no voltage is applied to the power terminals:
 - The power terminals U, V, W, RR+, and RR- remain live for at least 5 minutes after disconnecting from mains.
 - The power terminals L, N, U, V, W, T+, T-, RR+ and RR- remain live when the motor is stopped.
- The leakage current to earth (PE) is >3.5 mA. According to EN 50178 a fixed



installation is required and a double PE connection is required.

- The heat sink of the drive has an operating temperature of > 80 °C: Contact with the heat sink results in burns.

2 System Overview



Typical Servo System C14x0-XX: Servo Drive, Motor and Power Supply.

3 Functionality and Interfaces

	C1450-PN-VS-1S-000	C1450-PD-VS-1S-000	C1450-SC-VS-1S-000	C1450-IP-VS-1S-000	C1450-LU-VS-1S-000	C1450-EC-VS-1S-000	C1450-DS-VS-1S-000	C1450-SE-VS-1S-000	C1450-PL-VS-1S-000
Supply Voltage									
Motor Supply 1x230 VAC	•	•	•	•	•	•	•	•	•
Integrated Line Filter	•	•	•	•	•	•	•	•	•
Logic Supply 24VDC (22...26VDC)	•	•	•	•	•	•	•	•	•
Motor Phase Current (preliminary)									
15 A _{rms peak} (0-599Hz)	•	•	•	•	•	•	•	•	•
7.5 A _{rms continuous} (0-599Hz) (preliminary)	•	•	•	•	•	•	•	•	•
Controllable Motors									
LinMot P10-70x...(Motor Link C)	•	•	•	•	•	•	•	•	•
Selected motors (contact support)	•	•	•	•	•	•	•	•	•
Command Interface									
PROFINET	•								
PROFINET Profidrive		•							
SERCOS III			•						
ETHERNET IP				•					
LinUDP					•				
ETHERCAT						•			
ETHERCAT CiA402							•		
ETHERCAT SoE								•	
POWERLINK									•
Programmable Motion Profiles (Curves)									
Up to 100 Motion Profiles	•	•	•	•	•	•	•	•	•
Up to 16302 Curve Points	•	•	•	•	•	•	•	•	•
Programmable Command Table									
Command Table with up to 255 entries	•	•	•	•	•	•	•	•	•
External Position Sensor									
Incremental (RS422 up to 25 M counts/s)	•	•	•	•	•	•	•	•	•
Absolute (SSI, BiSS-B, BiSS-C, EnDat2.1, EnDat2.2)	•	•	•	•	•	•	•	•	•
Configuration Interface									
RS232	•	•	•	•	•	•	•	•	•
Ethernet (EoE, etc... depending on Interface)	•	•	•	•	•	•	•	•	•
Integrated Safety Functions (-1S Option)									
STO (2 Safety Relays)	•	•	•	•	•	•	•	•	•

4 Power Supply and Grounding



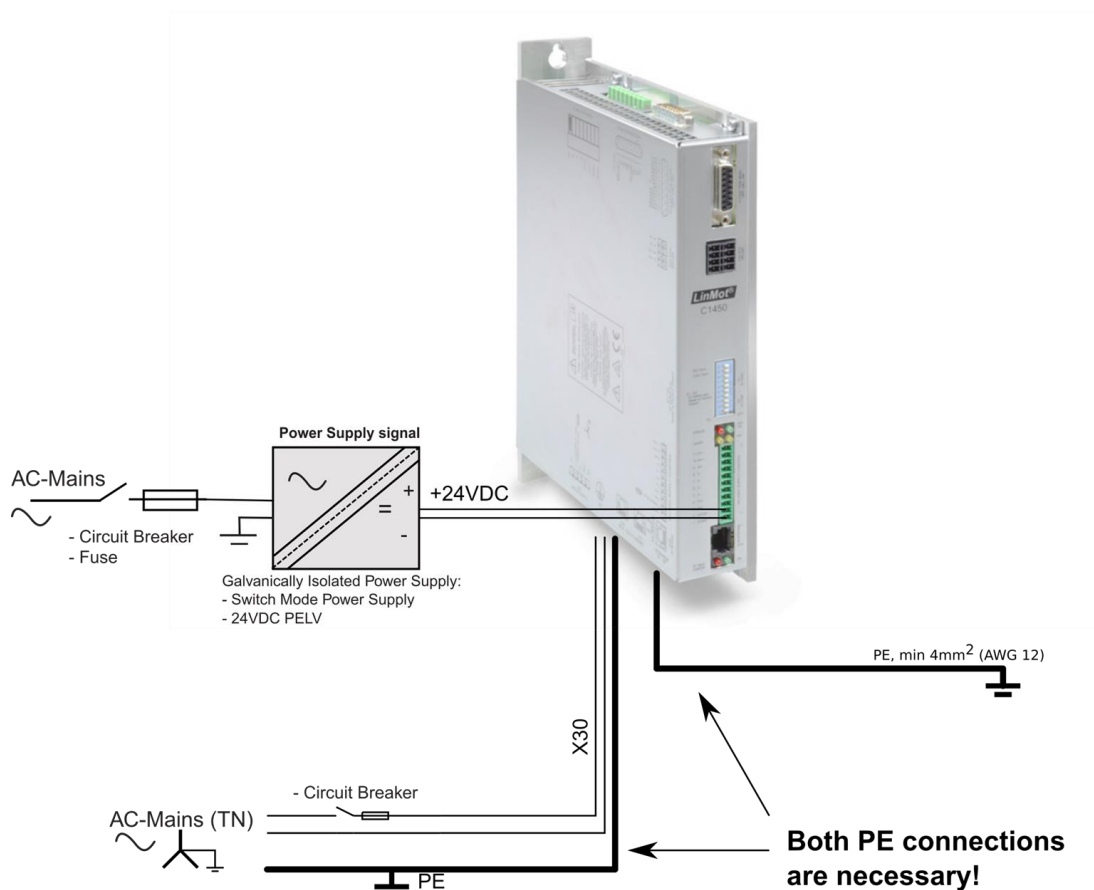
In order to assure a safe and error free operation, and to avoid severe damage to system components, **all system components must be well grounded to protective earth PE.** This includes both LinMot and all other control system components on the same ground bus.



The leakage current to earth (PE) is >3.5 mA. According to EN 50178 a fixed installation is required and **a double PE connection is required.** One PE connection is on X30, the second one is an M5 bolt on top of the housing.



Each system component should be tied directly to the ground bus (**star pattern**), rather than daisy chaining from component to component. (LinMot motors are properly grounded through their power cables when connected to LinMot drives.)

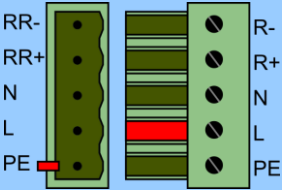


5 Description of the connectors / Interfaces

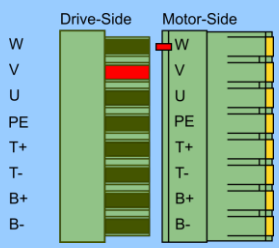
5.1 PE

PE	Protective Earth
PE	<ul style="list-style-type: none"> • Use min. 4mm² (AWG11) • Tightening torque: 2Nm (18 lbin)


5.2 X30

X30	Motor Supply Mains / Regeneration
	<p>RR- Regeneration Resistor RR+ Regeneration Resistor N: Neutral (TN system with grounded Neutral) L1: Line 1 (1x230VAC (+-10%) 50/60Hz / use slow blow 6A fuse) PE: PE, Protective Earth</p> <p>Line filter is integrated into the drive.</p>
Screw connector	<p>Screw Terminals:</p> <ul style="list-style-type: none"> - Tightening torque: 0.5 - 0.6 Nm - Screws: M3 - Use 60/75°C copper conductors only - Conductor cross-section: 2.5mm² (AWG 12) - Stripping length 7mm <p>LinMot Article Number: 0150-3607 (DC01-C1400/X30) Operating of the drive is only allowed with the above article! No other type of connector shall be used!</p>


5.3 X2

X2 Motor Phases	
	<p>W: Motor Phase W V: Motor Phase V U: Motor Phase U PE: Protective Earth T+: Temperature Sensor T+ T-: Temperature Sensor T- B+: Motor Brake+ B-: Motor Brake-</p>
Spring Cage Connector	<p>Important Notices:</p> <ul style="list-style-type: none"> The Shield of the motor cable has to be mounted with a surface as large as possible (low ohm, low impedance). Use an EMC shield clamp mounting (MC10-EMV/14-D / Art. Nr. 0150-3631). Max. cable length: 20m (may be limited by motor) Screw Terminals: <ul style="list-style-type: none"> Spring-cage connector Use 60/75°C copper conductors only Conductor cross-section: 0.2 – 2.5 mm² (depends on Motor current) / AWG 24 -12 Stripping length 10mm <p>Temperature sensors (thermistor) of the following types are supported:</p> <ul style="list-style-type: none"> KTY 83/84 PT1000 PTC (digital) <p>Attention: An isolated thermistor is necessary!</p> <ul style="list-style-type: none"> LinMot Article Number: 0150-3605 Operating of the drive is only allowed with the above article! No other type of connector shall be used!



5.4 X3

X3 Motor Encoder (Motor Link C) / Not available on -CI drives!																																								
	<table><tr><td>8</td><td>15</td><td>Motor Link C -</td></tr><tr><td>7</td><td>14</td><td>Motor Link C +</td></tr><tr><td>6</td><td>13</td><td>do not connect</td></tr><tr><td>5</td><td>12</td><td>do not connect</td></tr><tr><td>4</td><td>11</td><td>do not connect</td></tr><tr><td>3</td><td>10</td><td>GND Sense</td></tr><tr><td>2</td><td>9</td><td>+5V Sense</td></tr><tr><td>1</td><td>8</td><td>Cos-</td></tr><tr><td></td><td></td><td>Cos+</td></tr><tr><td></td><td></td><td>Sin-</td></tr><tr><td></td><td></td><td>Sin+</td></tr><tr><td></td><td></td><td>+5V</td></tr><tr><td></td><td></td><td>shield</td></tr></table>	8	15	Motor Link C -	7	14	Motor Link C +	6	13	do not connect	5	12	do not connect	4	11	do not connect	3	10	GND Sense	2	9	+5V Sense	1	8	Cos-			Cos+			Sin-			Sin+			+5V			shield
8	15	Motor Link C -																																						
7	14	Motor Link C +																																						
6	13	do not connect																																						
5	12	do not connect																																						
4	11	do not connect																																						
3	10	GND Sense																																						
2	9	+5V Sense																																						
1	8	Cos-																																						
		Cos+																																						
		Sin-																																						
		Sin+																																						
		+5V																																						
		shield																																						
DSUB-15 (m)	<ul style="list-style-type: none">Motor Link C is a high-speed serial communication protocol to the motor encoder.Max. cable length: see 5.3																																							

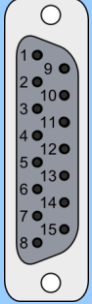
5.5 X4

X4 Logig Supply / IO Connection				
<div> <div> X4.11 X4.10 X4.9 X4.8 X4.7 X4.6 X4.5 X4.4 X4.3 +24VDC DGND </div>  <div>11</div> </div>	11 10 9 8 7 6 5 4 3 2 1	AnIn- AnIn+ AnIn In In In In Out Out +24VDC GND	X4.11 X4.10 X4.9 X4.8 X4.7 X4.6 X4.5 X4.4 X4.3 Supply Supply	Configurable Analog Input differentiell (with X4.10) Configurable Analog Input differentiell (with X4.11) Configurable Analog Input single ended Configurable Input Configurable Input Configurable Input Configurable Input Configurable Output Configurable Output Configurable Output Logic Supply 22-26 VDC Ground
Spring cage connector	<p>Inputs (X4.5 .. X4.8): 24V / 5mA (Low Level: -0.5 to 5VDC, High Level: 15 to 30VDC)</p> <p>Outputs (X4.3 .. X4.4): 24V / max.100mA, Peak 370mA (will shut down if exceeded)</p> <p>Analog Inputs: 12 bit A/D converted</p> <p>X4.9: Single ended analog input to GND, 0..10V, Input Resistance 51kOhm to GND</p> <p>X4.10/X4.11 Differential analog input, +/-10V, Common mode range +/- 5VDC to GND Input resistance 11.4kOhm for each signal to GND.</p> <ul style="list-style-type: none"> - Use 60/75°C copper conductors only - Conductor cross-section max. 1.5mm² - Stripping length: 10mm - The 24VDC supply for the control circuit (X4.2) must be protected with an external fuse (3A slow blow) <p>LinMot Article Number: 0150-3447 (DC01-Signal/X4) Operating of the drive is only allowed with the above article! No other type of connector shall be used</p>			

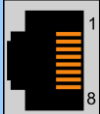
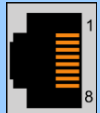
5.6 X33

X33 Safety Relays (only with the -1S option)				
<div> <div> X33.4/8 Ksr+ X33.3/7 Ksr- X33.2/6 Ksr f+ X33.1/5 Ksr f- </div>  <div>STO Relays</div> </div>	4 / 8 3 / 7 2 / 6 1 / 5	Ksr + Ksr - Ksr f+ Ksr f-		Safety Relay 1 / 2 Input positive Safety Relay 1 / 2 Input negative Safety Relay 1 / 2 feedback positive Safety Relay 1 / 2 feedback negative
Spring cage connector 	<ul style="list-style-type: none"> - Use 60/75°C copper conductors only - Conductor cross-section max. 1.5mm² (AWG 16) - Stripping length: 10mm - The state of the feedback contacts has to be checked after each change of the state of the control contacts! <p>- Never connect the safety relays to the logic supply of the drive!</p> <p>→ For detailed information see chapter 7 Safety Wiring.</p>			


5.7 X13

X13		External Position Sensor Differential Hall Switches	
	1	ABZ with Hall Switches	SSI / BiSS-B / BiSS-C / EnDat2.1 / EnDat2.2
	2	+5V DC	+5V DC
	3	A+	A+ (optional)
	4	A-	A- (optional)
	5	B+	B+ (optional)
	6	B-	B- (optional)
	7	Z+	Data+
	8	Z-	Data-
	9	Encoder Alarm (optional)	Encoder Alarm (optional)
	10	GND	GND
	11	U+	nc
	12	U-	nc
	13	V+	nc
	14	V-	nc
	15	W+	Clk+
		W-	Clk-
		Shield	Shield
DSUB-15 (f)		<p><u>Position Encoder Inputs (RS422):</u> Max Input Frequency: 25 M counts/s with quadrature decoding, 40ns edge separation</p> <p><u>Encoder Simulation Outputs (RS422):</u> Max Output Frequency: 4 M counts/s with quadrature decoding, 250ns edge separation</p> <p><u>Differential Hall Switch Inputs (RS422):</u> Input Frequency: <1kHz</p> <p><u>Enc. Alarm In:</u> 5V / 1mA</p> <p><u>Sensor Supply:</u> 5VDC max. 100mA / 5VDC max. 300mA (Since firmware version 6.7)</p>	





5.8 X17 - X18

X17 - X18		RealTime Ethernet 10/100 Mbit/s	
  RJ-45	X18 RT ETH Out	Specification depends on RT-Bus Type. Please refer to according documentation.	
	X17 RT ETH In		



5.9 X19

X19 System	
	1 Do not connect 2 Do not connect 3 RS232 Rx 4 GND 5 GND 6 RS232 Tx 7 Do not connect 8 Do not connect
RJ-45	Use isolated USB-RS232 converter (Art.-No. 0150-2473) for configuration over RS232.

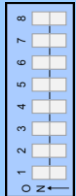
5.10 LEDs

LEDs	State Display		
Error   24VOK Warn   EN	Signal: 24VOK EN Warn Error	Color: Green Yellow Yellow Red	Description: 24V Logic Supply OK Motor Enabled / Error Code Low Nibble Warning / Error Code High Nibble Error

5.11 RT BUS LEDs

RT Bus LEDs	RT Bus State Display		
RT BUS   OK ERROR	Signal: OK RT BUS ERROR	Color: Green Red	Description: OK Error
The use of these LEDs depends on the type of fieldbus which is used. Please see the corresponding manual for further information.			

5.12 S1 - S2

S1 - S2	Address Selectors	
	S1 (5..8)	Bus ID High (0 ... F). Bit 5 is the LSB, bit 8 the MSB.
	S2 (1..4)	Bus ID Low (0 ... F). Bit 1 is the LSB, bit 4 the MSB.
The use of these switches depends on the type of fieldbus which is used. Please see the corresponding manual for further information.		

5.13 S5

S5	Bootstrap
	This switch is used for initial programming. Make sure the switch is in position "off". Otherwise the drive will not start up.

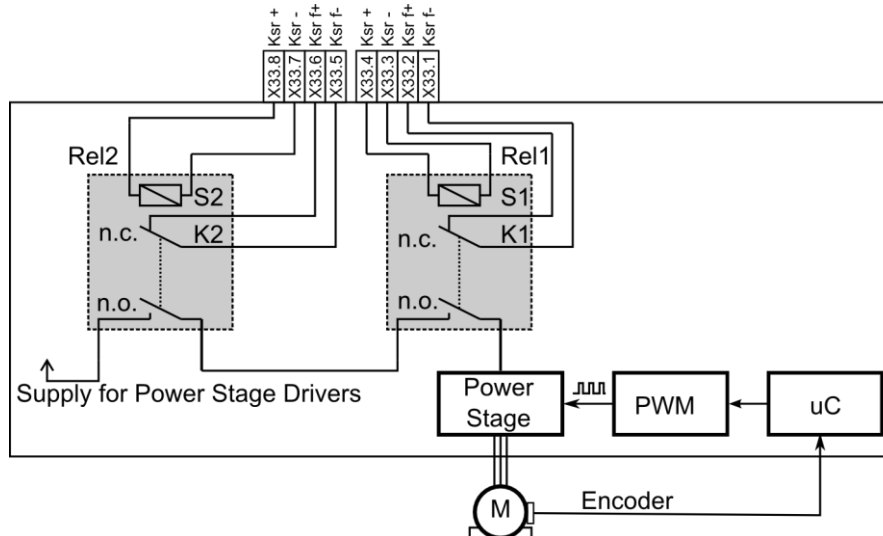
6 Error Codes

Error Codes			
<div> <div>Error</div> <div>Warn</div> <div>24VOK</div> <div>EN</div> </div>			
Error	Warn	EN	Description
Off	Warning	Operation Enabled	Normal Operation: Warnings and operation enabled are displayed.
On	<ul style="list-style-type: none"> • ~2Hz 0..15 x Error Code High Nibble 	<ul style="list-style-type: none"> • ~2Hz 0..15 x Error Code Low Nibble 	Error: The error code is shown by a blink code with "WARN" and "EN". The error byte is divided into low and high nibble (= 4 bit). "WARN" and "EN" are blinking together. The error can be acknowledged. (e.g.: WARN blinks 3x, EN blinks 2x; Error Code = 32h)
<ul style="list-style-type: none"> • ~2Hz 	<ul style="list-style-type: none"> • ~2Hz 0..15 x Error Code High Nibble 	<ul style="list-style-type: none"> • ~2Hz 0..15 x Error Code Low Nibble 	Fatal Error: The error code is shown by a blink code with "WARN" and "EN". The error byte is divided into low and high nibble. "WARN" and "EN" are blinking together. Fatal errors can only be acknowledged by a reset or power cycle. (e.g.: WARN blinks 3x, EN blinks 2x; Error Code = 32h)
<ul style="list-style-type: none"> • ~4Hz 	<ul style="list-style-type: none"> • ~2Hz 0..15 x Error Code High Nibble 	<ul style="list-style-type: none"> • ~2Hz 0..15 x Error Code Low Nibble 	System Error: Please reinstall firmware or contact support.
<ul style="list-style-type: none"> • ~0.5Hz 	<ul style="list-style-type: none"> • ~0.5Hz 	On	Signal Supply 24V too low: The error and warn LEDs blink alternating if the signal supply +24V (X4.2) is less than 18VDC.
Off	*•••	•*••	Plug&Play Communication Active This sequence (Warn on, then En on, then both off, complete sequence of the 4 states ca. 1Sec) signals the state when the plug and play parameters are being read from the motor.
<ul style="list-style-type: none"> *• ~4Hz 	<ul style="list-style-type: none"> •* ~4Hz 	Off	Waiting for Defaulting Parameters When ID (S1, S2) is set to 0xFF, the drive starts up in a special mode and the Error and Warn LED blink alternating ~4Hz. When the ID is set to 0x00, all parameters will be set to their default value. To leave this state, power down the drive and change the ID. Also see in the Usermanual_LinMot-Talk under chapter trouble shooting.
Off	<ul style="list-style-type: none"> *• ~2Hz 	<ul style="list-style-type: none"> *• ~2Hz 	Defaulting Parameters Done When the parameters have set to their default values (initiated via S1/S2 on power up) the Warn and En LEDs blink together at 2 Hz. To leave this state, power down the drive. Also see in the Usermanual_LinMot-Talk under chapter trouble shooting.
On	On	On	Bootstrap If also both RT LEDs are on, the drive is in the bootstrap mode. Set S5 to off.

The meaning of the error codes can be found in the "0185-1093-E_6V5_MA_MotionCtrlSW-SG5-SG7.pdf" and the user manual of the installed interface software. These documents are provided together with LinMot-Talk configuration software and can be downloaded from www.linmot.com.

7 Safety Wiring

The C1400 Drive with the -1S option has internal safety functions:
Two Safety relays Ksr in series, which support the supply voltage for the motor drivers. There are also two feedback contacts for each relay, which have to be.



To enable the -1S drives both relays have to be switched on.
Minimal wiring:

- Connect X33.8 and X33.4 to 24VDC (from safety)
- Connect X33.7 and X33.3 to GND (from safety)



Attention: Never connect X33.8 and X33.4 to the logic supply of X4!

If an over voltage protection is needed, it must be provided externally and sized according the safety circuit of the machine!

Attention: The drop out time of the relays is depending on the external circuitry!

Safety Relay Ksr	
Nominal voltage	24 VDC
Min. pick-up voltage at 20°C	≤ 16.8V
Drop-out voltage at 20°C	≥ 2.4 V
Drop-out time (no protection circuit)	Typ. 3ms
Coil resistance at 20°C	2'100 Ω ± 10%
Type	EN 50205, type A
Contact lifetime	> 10'000'000
Manufacturer and type	Elesta relays / SIS112 24VDC

Drive Classification according EN ISO 13849-1 (safety of machinery)	
Category	cat = 3
Performance Level	PL = d
Diagnostic Coverage	DC = high
Mean Time to hazardous failure of one channel	MTTFd = high (100 years typically, see calculation example below)

DC (Diagnostic Coverage) is high (99%) assuming that the state of the feedback contacts is checked after each change of the state of the control contacts.

MTTF_d mainly depends on the number of operations of the safety relays.

Example calculation of MTTF_d:

Assuming that the safety function is requested every 20s on a machine running 24h per day and 7 days per week.

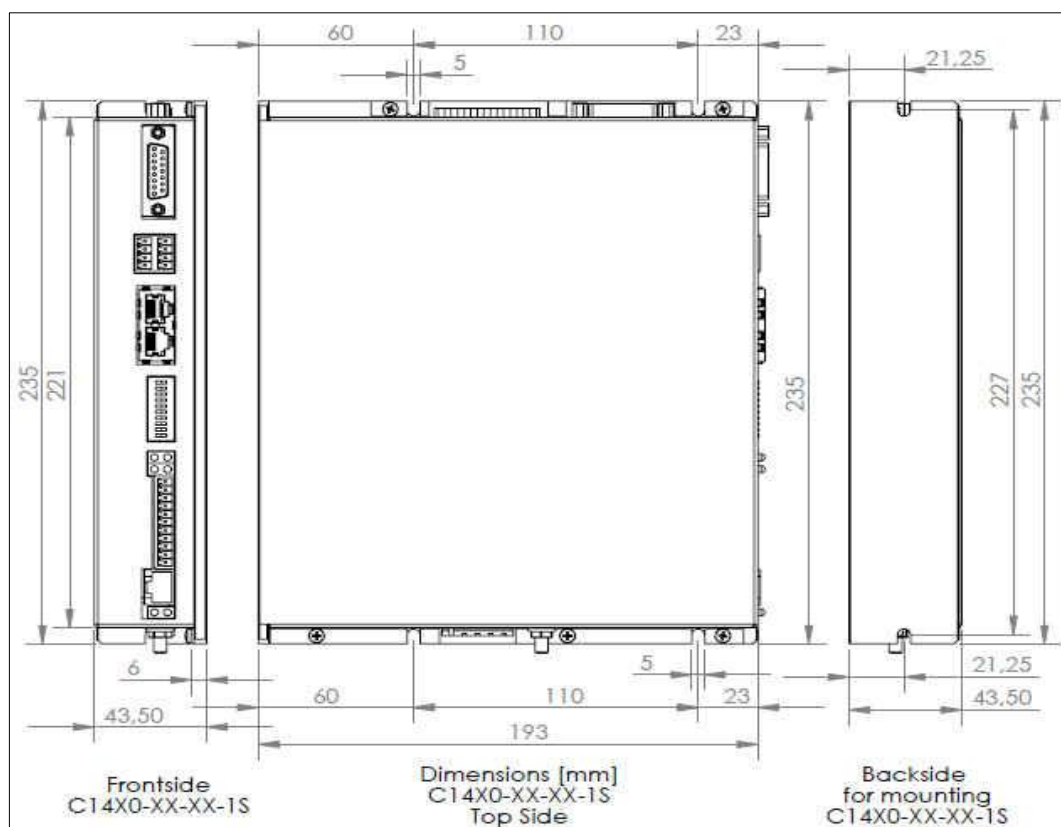
$$B_{10} = 10'000'000$$

$$B_{10d} = 20'000'000 \text{ (according EN ISO 13849-1:2008 table C.1)}$$

$$n_{op} \text{ per year} = (24h/day * 365.25days/year * 3600s/h) / 20s = 1'577'880 \text{ operations}$$

$$\begin{aligned} MTTF_d &= B_{10d} / (0.1 \times n_{op}) = 126.75 \text{ years (this has to be limited to 100years} \\ &\quad \text{according the standard for further calculations)} \\ &= \text{high (100 years)} \end{aligned}$$

8 Physical Dimensions



C1400 Series single axis drive

		C14X0-XX-XX-1S
Width	mm (in)	43.5 (1.71)
Height	mm (in)	235 (9.25)
Depth	mm (in)	193 (7.60)
Weight	kg (lb)	1.9 (4.1)
Mounting		Backside 2 x M4 Bottom Side 4x M4
Case	IP	20
Storage Temperature	°C	-25...40
Transport Temperature	°C	-25...70
Operating Temperature	°C	0...40
Relative humidity		95% (non-condensing)
Pollution	IEC/EN 60664-1	Pollution degree 2
Shock resistance (16ms)	-1S option	2g
Vibration resistance (10-200Hz)	-1S option	1g
Max. Case Temperature	°C	90
Max. Power Dissipation	W	100
Mounting place		In the control cabinet
Mounting position		vertical
Distance between drives	mm (in)	≥ 200 (8) top / bottom Drives with fan can be mounted vertically side by side

9 Power Supply Requirements

Motor Power Supply

Direct AC mains connection: 1/PE AC 230V (±10%) / 50-60Hz / TN System



Only 1-phase supply is supported! The mains must be a symmetrical four-wire system with grounded neutral.

DC Supply (for example 72VDC) for initial test setups can be supplied through the 1-phase supply connector.

Use a slow blow 6A fuse and conductor cross section of 2.5mm² for mains connections!

Max. motor cable length: see 5.3

Signal Power Supply

The logic supply needs a regulated power supply of a nominal voltage of 24 VDC. The voltage must be between 22 and 26 VDC.

Current to be provided from the supply:

min. 1A	(no load on the outputs)
typ. 1.5A	(all 10 outputs "on" with 100mA load and /Break with no load)
max. 2.5A	(all 10 outputs "on" with 100mA load and /Break with 1A load)

The 24VDC supply for the control circuit must be protected with an external fuse (3A slow blow)

10 Regeneration of Power / Regeneration Resistor

For regeneration use only the following type of resistor (no other type is allowed):

Item	Description	Art. No.
Regeneration Resistor	RR01-68/100 (68 Ohm, 100 W, 1000V) for C1400	0150-3581

11 Ordering Information



Item	Description	Art. No.
C1450-SE-VS-1S-000	EtherCAT SoE Drive (1x230V/20A), STO	0150-2660
C1450-SC-VS-1S-000	Sercos III Drive (1x230V/20A), STO	0150-2659
C1450-PN-VS-1S-000	ProfiNet Drive (1x230V/20A), STO	0150-2658
C1450-PL-VS-1S-000	POWERLINK Drive (1x230V/20A), STO	0150-2656
C1450-PD-VS-1S-000	PROFIdrive Drive (1x230V/20A), STO	0150-2664
C1450-IP-VS-1S-000	Ethernet/IP Drive (1x230V/20A), STO	0150-2666
C1450-EC-VS-1S-000	EtherCAT Drive (1x230V/20A), STO	0150-2657
C1450-DS-VS-1S-000	EtherCAT CoE Drive (1x230V/20A), STO	0150-2665
C1450-LU-VS-1S-000	LinUDP Drive (1x230V/20A), STO	0150-2667
Accessories	Description	Art. No.
Isolated USB-RS232 converter	Isolated USB RS232 converter with config. cable	0150-2473
RR01-68/100	Regeneration resistor (68R, 100W, 1000V) for C1400	0150-3581
DC01-C1400/X4/X30/X33	Drive Connector Set for C1400-1S	0150-3677
DC01-C1400/X2	Drive Connector Motor Phases	0150-3605
DC01-E1400/X4	Drive Connector 24VDC & Logic	0150-3447
DC01-C1400/X30	Drive Connector Mains Supply (1x230VAC)	0150-3607
MC10-EMV/14-D	Shield clamp for P10 motor power cable	0150-3631

Bold items are strongly recommended accessories!



ATTENTION: The connectors have to be ordered separately and are not included with the drive!
Use isolated USB RS232 converter for configuration!

12 International Certifications

Certifications	
Europe 	See chapter "13 EU Declaration of Conformity CE-Marking"
UK 	See chapter 15 UK Declaration of Conformity UKCA-Marking
IECEE CB SCHEME	Ref. Certif. No. CH-8095



Ref. Certif. No.

CH-8095

IEC SYSTEM FOR MUTUAL RECOGNITION OF TEST
CERTIFICATES FOR ELECTRICAL EQUIPMENT
(IECEE) CB SCHEME

SYSTEME CEI D'ACCEPTATION MUTUELLE DE
CERTIFICATS D'ESSAIS DES EQUIPMENTS
ELECTRIQUES (IECEE) METHODE OC

CB TEST CERTIFICATE / CERTIFICAT D'ESSAI OC

Product
Produit

Servo controller for linear motors

Name and address of the applicant
Nom et adresse du demandeur

NTI AG Linmot SWITZERLAND

Haerdlistrasse 15
8957 Spreitenbach

Name and address of the manufacturer
Nom et adresse du fabricant

NTI AG Linmot SWITZERLAND

Haerdlistrasse 15
8957 Spreitenbach

Name and address of the factory
Nom et adresse de l'usine

NTI AG Linmot SWITZERLAND

Haerdlistrasse 15
8957 Spreitenbach

Note: When more than one factory, please report on page 2
Note: Lorsque il y plus d'une usine, veuillez utiliser la 2^{ème} page

☐ Additional Information on page 2

Ratings and principal characteristics
Valeurs nominales et caractéristiques principales

200-240 VAC, 50-60 Hz, 6 A
24 VDC, 3 A via ext. power supply
Class I

Trade mark (if any)
Marque de fabrique (si elle existe)

LinMot

Type of Manufacturer's Testing Laboratories used
Type de programme du laboratoire d'essais constructeur

Model / Type Ref.
Ref. de type

C14xx-xx-VS-xS-xxx

Additional information (if necessary may also be reported on page 2)

Les informations complémentaires (si nécessaire, peuvent être indiqués sur la 2^{ème} page

☒ Additional Information on page 2

A sample of product was tested and found to be in conformity with IEC
Un échantillon de ce produit a été essayé et a été considéré conforme à la CEI

61000-6-2(ed.2)
61000-6-4(ed.2);am1
61000-6-7(ed.1)

National differences / Comments
Les différences nationales / Commentaires

EU Group Differences;
EU Special National Conditions;
EU A-Deviations

As shown in the Test Report Ref. No. which forms part of this Certificate
Comme indiqué dans le Rapport d'essais numéro de référence qui constitue partie de ce Certificat

15-EL-0165.E01 + .E02 + .Z01

This CB Test Certificate is issued by the National Certification Body
Ce Certificat d'essai OC est établi par l'Organisme National de Certification

Electrosuisse
Luppenstrasse 1,
8320 Fehraltorf
SWITZERLAND

Signed by: Martin Plüss
2016-01-28





Ref. Certif. No.

CH-8095

Additional information (if necessary)

Information complémentaire (si nécessaire)

Product Family

Type:	Explanation:
C1450-IP-VS-0S-000	Ethernet/IP Drive
C1450-PL-VS-0S-000	Powerlink Drive-
C1450-EC-VS-0S-000	EtherCAT Drive
C1450-PN-VS-0S-000	ProfNET Drive
C1450-SC-VS-0S-000	Sercos III Drive
C1450-SE-VS-0S-000	EtherCAT SoE Drive
C1450-PD-VS-0S-000	PROFIdrive Drive
C1450-DS-VS-0S-000	EtherCAT CoE Drive
C1450-LU-VS-0S-000	LinUDP Drive
C1400-CO-VS-0S-000	CAN-Bus Drive
C1450-IP-VS-1S-000	Safety Ethernet/IP Drive
C1450-PL-VS-1S-000	Safety Powerlink Drive-
C1450-EC-VS-1S-000	Safety EtherCAT Drive
C1450-PN-VS-1S-000	Safety ProfNET Drive
C1450-SC-VS-1S-000	Safety Sercos III Drive
C1450-SE-VS-1S-000	Safety EtherCAT SoE Drive
C1450-PD-VS-1S-000	Safety PROFIdrive Drive
C1450-DS-VS-1S-000	Safety EtherCAT CoE Drive
C1450-LU-VS-1S-000	Safety LinUDP Drive
C1400-CO-VS-1S-000	Safety CAN-Bus Drive

Nomenclature

Code	Description
C1400-	Drive type (Equipment containing Ethernet has an xxx50)
GP-	Interface
LC-	Power output
1S-	Functional safety option
000	Individual extension (e.g. customer related firmware option etc.)

Interfaces:

Code	Abbr.	Description
0	CO	CANopen
50	DS	ETHERCAT CoE Drive
50	EC	ETHERCAT
50	PN	ProfNet
50	SE	SERCOS over ETHERCAT
50	PL	POWERLINK
50	PN	Profinet
50	PD	Profinet mit Profidrive
50	IP	ETHERNET IP
50	SC	SERCOS III

 This CB Test Certificate is issued by the National Certification Body
 Ce Certificat d'essai OC est établi par l'Organisme National de Certification

 Electrosuisse
 Luppenstrasse 1,
 8320 Fehraltorf
 SWITZERLAND

 Signed by: Martin Plüss
 2016-01-28





Declaration of Conformity to the EtherNet/IP™ Specification

ODVA hereby issues this Declaration of Conformity to *The EtherNet/IP™ Specification* for the product(s) described below. The Vendor listed below (the "Vendor") holds a valid Terms of Usage Agreement, which is incorporated herein by reference, for the EtherNet/IP Technology from ODVA, thereby agreeing that it is the Vendor's ultimate responsibility to assure that its EtherNet/IP Compliant Products conform to *The EtherNet/IP Specification* and that *The EtherNet/IP Specification* is provided by ODVA to the Vendor on an AS IS basis without warranty. NO WARRANTIES, EXPRESSED OR IMPLIED, INCLUDING WITHOUT LIMITATION ANY WARRANTIES OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE, ARE BEING PROVIDED BY ODVA.

In recognition of the below EtherNet/IP Compliant Product(s) having been EtherNet/IP Conformance Tested at ODVA-authorized Test Service Provider and having received a passing result from ODVA at the Composite Test Revision Level specified below, this Declaration of Conformity authorizes the Vendor to use the EtherNet/IP Certification Marks in conjunction with the specific EtherNet/IP Compliant Product(s) described below, for so long as the Vendor's Terms of Usage Agreement for the EtherNet/IP Technology remains valid.



Certification Logo Mark

EtherNet/IP CONFORMANCE TESTED™

Certification Word Mark

This Declaration of Conformity is issued on February 2, 2015 on behalf of ODVA by:

Katherine Voss
Executive Director

Vendor Information				
Vendor Name	NTI Limited			
Test Information				
Test Date	December 11, 2014			
Composite Test Revision	CT11			
ODVA File Number	11332.01			
Product Information				
Network Category:			Node	
Identity Object Instance				
Vendor ID (Attribute 1)	589			
Device Type (Attribute 2)	0x2B			
Device Profile Name	Generic Device (keyable)			
Products Covered under this Declaration of Conformity (Identity Object Instance)				
No.	Product Code (Attribute 3)	Product Name (Attribute 7)	Product Revision (Attribute 4)	SOC File Name
1	1886	C1250IPXC0S	1.001	C1250IPXC0S.stc
2	2346	C1250IPXC1S	1.001	C1250IPXC1S.stc
3	1761	E1250-IP-UC	1.001	Not Tested
4	1782	E1450IPQN0S	1.001	Not Tested
5	2354	E1450IPQN1S	1.001	Not Tested
6	2610	C1450IPQN0S	1.001	Not Tested
7	2611	C1450IPQN1S	1.001	Not Tested
8	2612	C1450IPQD0S	1.001	Not Tested
9	2613	D1450IPVR0S	1.001	Not Tested
10	2614	D1450IPQD0S	1.001	Not Tested
11	2615	D1250IPXC0S	1.001	Not Tested

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PUB00033R7

www.odva.org

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13 EU Declaration of Conformity CE-Marking

NTI AG / LinMot®
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Tel.: +41 (0)56 419 91 91
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declares under sole responsibility the compliance of the products:

Servo Drives of the Series C1450-xx-VS-1S-xxx

with the

Low Voltag Directive 2014/35/EU

Applied harmonized standard:

EN 61800-5-1: 2007

EMC Directive 2014/30/EU

Applied harmonized standards:

EN 61000-6-2: 2005 (Immunity for industrial environments)

EN 61000-6-4: 2007 + A1:2011 (Emission for industrial environments)

According to the EMC directive, the listed devices are not independently operable products.

Compliance of the directive requires the correct installation of the product, the observance of specific installation guides and product documentation. This was tested on specific system configurations.

The safety instructions of the manuals are to be considered.

The product must be mounted and used in strict accordance with the installation instructions contained within the installation guide, a copy of which may be obtained from NTI AG.

Company: NTI AG
Spreitenbach, 11.04.2016



Dr. Ronald Rohner / CEO NTI AG



Dr. Marco Hitz / Responsible for documentation

14 UK Declaration of Conformity UKCA-Marking

NTI AG / LinMot®
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8957 Spreitenbach
Switzerland
Tel.: +41 (0)56 419 91 91
Fax: +41 (0)56 419 91 92

declares under sole responsibility the compliance of the products:

- Drives of the Series **E14x0-xx-QN-xS-xxx**

with the

Electrical Equipment (Safety) Regulations 2016 SI 2016 No. 1101

Applied designated standards:

- **EN 61800-5-1: 2007**

EMC Regulation S.I. 2016 No. 1091.

Applied designated standards:

- **EN 61000-6-2: 2005 (Immunity for industrial environments)**
- **EN 61000-6-4: 2007 + A1:2011 (Emission for industrial environments)**

According to the EMC regulation, the listed devices are not independently operable products.

Compliance of the regulation requires the correct installation of the product, the observance of specific installation guides and product documentation. This was tested on specific system configurations.

The safety instructions of the manuals are to be considered.

The product must be mounted and used in strict accordance with the installation instructions contained within the installation guide, a copy of which may be obtained from NTI AG.

Company: NTI AG
Spreitenbach, 23.03.2022



Dr. Ronald Rohner / CEO NTI AG



Dr. Marco Hitz / Responsible for documentation

15 Contact Addresses

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Please visit <http://www.linmot.com/> to find the distributor closest to you.

Smart solutions are...

